## Brans-Dicke Theory

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## 1 Equations of Motion

Here we are interested in deriving the Brans-Dicke equations of motion. First we start off with the Lagrangian for Brans-Dicke

$$\mathcal{L} = \sqrt{-g} \bigg( \phi R - \frac{\omega}{\phi} \nabla_{\mu} \phi \nabla^{\mu} \phi + \mathcal{L}_m \bigg).$$
(1)

where  $\phi$  is a scalar field,  $R = R^{\mu}{}_{\mu} = g^{\mu\nu}R_{\mu\nu}$  is the Ricci scalar,  $\omega$  is a dimensionless parameter and  $\mathcal{L}_m$  is the Lagrangian for matter. Next we place the Lagrangian in the action.

$$S = \int \sqrt{-g} (\phi R - \frac{\omega}{\phi} \nabla_{\mu} \phi \nabla^{\mu} \phi + \mathcal{L}_m) \, \mathrm{d}^4 x.$$
<sup>(2)</sup>

We will soon vary with respect to the inverse metric. But first we recognize that  $R = g^{\mu\nu}R_{\mu\nu}$ . So we then have

$$S = \int \sqrt{-g} \left( \phi g^{\mu\nu} R_{\mu\nu} - \frac{\omega}{\phi} g^{\mu\nu} \nabla_{\mu} \phi \nabla_{\nu} \phi + \mathcal{L}_m \right) \mathrm{d}^4 x \,. \tag{3}$$

Now we shall vary the action with respect to the inverse metric

$$\delta S = \delta S_{\phi R} + \delta S_{\phi} + \delta S_M \tag{4}$$

where

$$\delta S_{\phi R} = \int (\phi R_{\mu\nu} \delta g^{\mu\nu} + \phi g^{\mu\nu} \delta R_{\mu\nu}) \sqrt{-g} + \phi R \delta \sqrt{-g} d^4 x,$$
  
$$\delta S_{\phi} = \int -\frac{\omega}{\phi} \nabla_{\mu} \phi \nabla_{\nu} \phi \, \delta g^{\mu\nu} \sqrt{-g} - \frac{\omega}{\phi} \nabla_{\mu} \phi \nabla^{\mu} \phi \, \delta \sqrt{-g} \, d^4 x$$
(5)

and  $S_M$  is the action for matter. The second term in  $S_{\phi R}$  can be found in Carroll's book. Using the result from there we find  $\delta S_{\phi R}$  takes the form

$$\delta S_{\phi R} = \int (\phi R_{\mu\nu} \delta g^{\mu\nu} + \nabla_{\rho} [g_{\mu\nu} \nabla^{\rho} \phi \delta g^{\mu\nu} - \nabla_{\lambda} \phi \delta g^{\rho\lambda}] \sqrt{-g} - \frac{1}{2} \phi R \sqrt{-g} g_{\mu\nu} \delta g^{\mu\nu}) d^4x$$

$$= \int (\phi R_{\mu\nu} - \frac{1}{2} \phi R g_{\mu\nu} - [\nabla_{\mu} \nabla_{\nu} \phi - g_{\mu\nu} \nabla^2 \phi]) \sqrt{-g} \delta g^{\mu\nu} d^4x.$$
(6)

Looking now to  $\delta S_{\phi}$ , the action becomes

$$\delta S_{\phi} = -\int \frac{\omega}{\phi} (\nabla_{\mu} \phi \nabla_{\nu} \phi - \frac{1}{2} g_{\mu\nu} (\nabla \phi)^2) \sqrt{-g} \delta g^{\mu\nu} \, \mathrm{d}^4 x, \tag{7}$$

with  $\nabla_{\mu}\phi\nabla^{\mu}\phi = (\nabla\phi)^2$ . Recall that the functional derivative of the action satisfies

$$\delta S = \int \sum_{i} \left( \frac{\delta S}{\delta \Psi^{i}} \, \delta \Psi^{i} \right) \mathrm{d}^{d} x \,, \tag{8}$$

where  $\{\Psi^i\}$  is a complete set of fields being varied. This brings the total action  $\delta S$  to be

$$\frac{1}{\sqrt{-g}}\frac{\delta S}{\delta g^{\mu\nu}} = \phi \left(R_{\mu\nu} - \frac{1}{2}Rg_{\mu\nu}\right) - \left(\nabla_{\mu}\nabla_{\nu}\phi - g_{\mu\nu}\nabla^{2}\phi\right) - \frac{\omega}{\phi}(\nabla_{\mu}\phi\nabla_{\nu}\phi - \frac{1}{2}g_{\mu\nu}(\nabla\phi)^{2}) + \frac{1}{2\sqrt{-g}}\frac{\delta S_{M}}{\delta g^{\mu\nu}} = 0.$$
(9)

Defining the energy momentum tensor to be

$$T_{\mu\nu} = -\frac{1}{\sqrt{-g}} \frac{\delta S_M}{\delta g^{\mu\nu}} \tag{10}$$

Moving the last terms to the other side and dividing both sides by  $\phi$ , we get

$$R_{\mu\nu} - \frac{1}{2}Rg_{\mu\nu} = \frac{1}{2\phi}T_{\mu\nu} + \frac{1}{\phi}(\nabla_{\mu}\nabla_{\nu}\phi - g_{\mu\nu}\nabla^{2}\phi) + \frac{\omega}{\phi^{2}}\left(\nabla_{\mu}\phi\nabla_{\nu}\phi - \frac{1}{2}g_{\mu\nu}(\nabla\phi)^{2}\right)$$
(11)

## 2 Degrees of Freedom

Brans-Dicke theory was one of the earliest competitors to GR. It is discussed today because it represent the prototypical example of a scalar tensor theory. The Lagrangian for the theory is given by

$$\mathcal{L} = \sqrt{-g} \bigg( \phi R - \frac{\omega}{\phi} \nabla_{\mu} \phi \nabla^{\mu} \phi \bigg).$$
(12)

We wish to expand all the terms to at most second order in  $\phi$ , R, and  $\sqrt{-g}$ . This brings us to

$$g_{\mu\nu} = \eta_{\mu\nu} + h_{\mu\nu},\tag{13}$$

$$\phi = \phi_o + \varphi, \tag{14}$$

$$\sqrt{-g} = 1 + \frac{1}{2}h + \frac{1}{8}h^2 - \frac{1}{4}h_{\mu\nu}h^{\mu\nu}, \qquad (15)$$

$$R = R^{(0)} + R^{(1)} + R^{(2)}, (16)$$

where  $\eta$  and  $\phi_o$  is some flat space solution,  $h_{\mu\nu}$  and  $\varphi$  are perturbations and taken to be much less than 1,  $h = h^{\mu}{}_{\mu} = \eta^{\mu\nu}h_{\mu\nu}$  is the trace , and  $R^{(0)} = 0$ ,  $R^{(1)}$ ,  $R^{(2)}$  are the zeroth, first, and second order curvature respectively. Keeping only the terms quadratic in both  $h_{\mu\nu}$ and  $\varphi$ , the Lagrangian becomes

$$\mathcal{L} = \phi_o (\sqrt{-g}R)^{(2)} - \frac{\omega}{\phi_o} \partial_\mu \varphi \partial^\mu \varphi.$$
(17)

Lets split these Lagrangians off into different sectors in order to deal with them easily.

$$\mathcal{L}_{R^{(2)}} = \phi_o(\sqrt{-g}R)^{(2)},\tag{18}$$

$$\mathcal{L}_{\varphi} = -\frac{\omega}{\phi_o} \partial_{\mu} \varphi \partial^{\mu} \varphi, \tag{19}$$

Since we've done the degree of freedom count for  $\mathcal{L}_{R^{(2)}}$  (being multiplied by a constant background won't change any of the calculations) we only need to focus our attention on  $\mathcal{L}_{\varphi}$ . We next perform the following decompositions:

$$h_{00} = h^{00} = 2\Phi, \tag{20}$$

$$h_{0i} = -h_i^0 = w_i, (21)$$

$$h = h^{\mu}{}_{\mu} = \eta^{\mu\nu} h_{\mu\nu} = -2\Phi + \bar{h}, \qquad (22)$$

$$w_i = w_i^T + \partial_i \Lambda, \tag{23}$$

$$h_{ij} = h_{ij}^{TT} + \partial_i v_j^T + \partial_j v_i^T + 2\left(\partial_i \partial_j \Psi - \frac{1}{3}\nabla^2 \Psi \delta_{ij}\right) + \frac{1}{3}\bar{h}\delta_{ij},\tag{24}$$

$$\partial^i h_{ij}^{TT} = \delta^{ij} h_{ij}^{TT} = \partial^i v_i^T = \partial^i w_i^T = 0, \qquad (25)$$

where  $\bar{h} = Tr[h_{ij}]$  and  $\delta_{ij}$  is the identity matrix. Defining the following gauge invariant fields

$$J \equiv \Phi - \dot{\Lambda} + \ddot{\Psi}, \qquad L \equiv \frac{1}{3}(\bar{h} - 2\nabla^2 \Psi), \qquad M_i \equiv w_i^T - \dot{v}_i^T.$$
(26)

We're ready to start our analysis on the degrees of freedom in these actions. We can turn our gaze to  $\mathcal{L}_{R^{(2)}}$  and using the results from the linearized GR calculation while also scaling by the constant background  $\phi_o$  we get the following actions:

$$S_T = \int \frac{1}{2} h_{TT}^{ij} \Box h_{ij}^{TT} \,\mathrm{d}^4 x,\tag{27}$$

$$S_V = \int \frac{1}{2} (\partial_i M_j)^2 \, \mathrm{d}^4 x, \qquad (28)$$

$$S_S = \int 4J\nabla^2 L - L\nabla^2 L - 2\dot{L}^2 \,\mathrm{d}^4 x,\tag{29}$$

$$S_{\varphi} = \int \frac{\omega}{\phi_o} \varphi \Box \varphi \, \mathrm{d}^4 x. \tag{30}$$

We can now analyze the true degrees of freedom that are present in  $h_{\mu\nu}$ . First, looking at the vector action we can see that no time derivatives of  $M_i$  are present in the action. Therefore it is an auxiliary field and we may use its equations of motion (EOM) to eliminate it. Proceeding accordingly we find

$$\frac{\delta \mathcal{L}}{\delta M^i} = \nabla^2 M_i = 0 \Rightarrow M_i = 0, \tag{31}$$

which implies that  $S_V = 0$ . Next we turn our attention to the scalar action. Since J appears linearly with no time derivatives, we may interpret it as a Lagrange multiplier. From there we can see that the EOM of J enforces the following constraint:

$$\frac{\delta \mathcal{L}}{\delta J} = \nabla^2 L = 0 \Rightarrow L = 0, \tag{32}$$

and therefore,  $S_S = 0$ . The total action is now  $S = S_T + S_{\varphi}$  and thus we can say that the Lagrangian for linearized Brans-Dicke has in total, three degrees of freedom. two from  $h_{ij}^{TT}$  and one from  $\varphi$ .